

Petri Hypernets for modeling mobile agents

Lucia Pomello

Università degli Studi di Milano - Bicocca
Dipartimento di Informatica, Sistemistica e Comunicazione

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Joint work with:

Marek Bednarczyk
Wiesław Pawłowski

Polish Academy of Science
IPI-PAN Gdańsk

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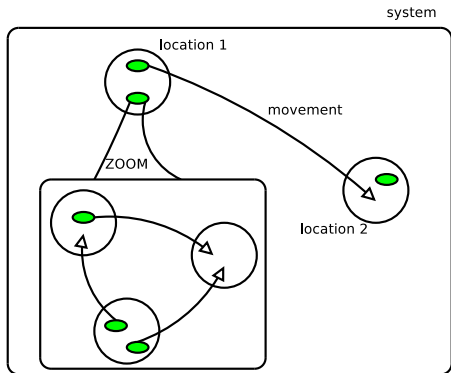
* now at CERN
(Centre Européen Recherche Nucléaire)

Petri Hypernets for modeling mobile agents

Outline

- 1 Systems of mobile agents
- 2 Petri Hypernets, the model
- 3 from Petri Hypernets to a basic class of Petri nets
- 4 Generalized hypernets
- 5 Two case studies
- 6 Conclusions

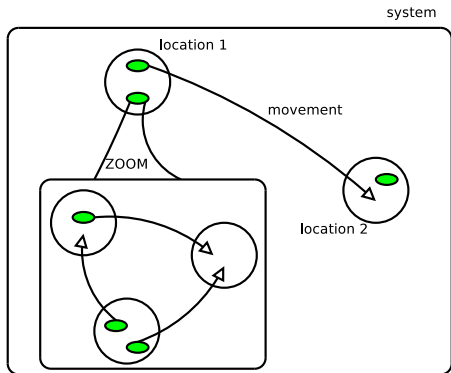
Systems of Mobile Agents



Main concepts

- Agents are *autonomous* and *interacting*
- They are embedded into *locations*
- *Mobility* means an agent can change its location
- *Hierarchical* structure which may *change*

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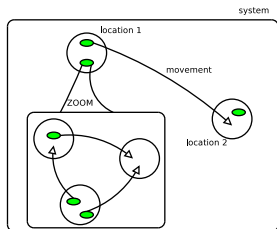
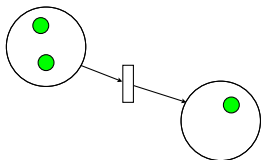
Main aim

- A *formal* model based on *Petri net theory* for systems of mobile agents

The Nets-within-nets Paradigm¹ and Mobile Agents

The Nets-within-nets Paradigm

- Petri Nets \implies Nets-within-nets
- Tokens of a Petri net can be nets themselves



Modeling Mobile Agents

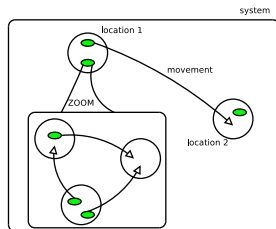
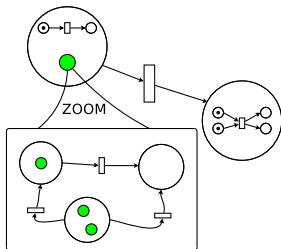
- Agents modeled as *nets*, which are *tokens* inside other agents
- Environment is a special agent
- Hierarchy of nets/agents

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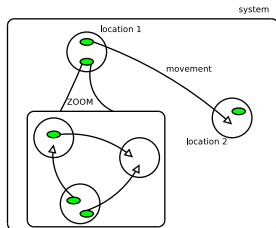
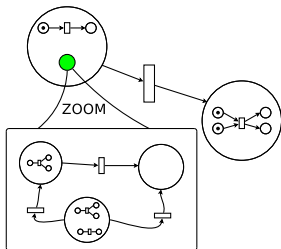
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SECTION 2

Petri Hypernets, the model

Petri Hypernets – introduction

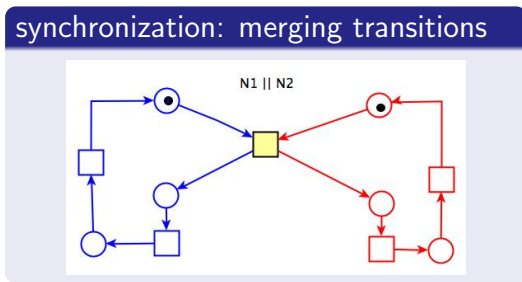
$$\langle \mathcal{N}, \mu \rangle$$

- Hypernet \mathcal{N} : a set of *agents*
- Agent A : a *net*, synchronous product of state-machine nets (*modules*)

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- Typing
 $\sigma_1 : \text{Agents} \rightarrow \text{Sorts}$
 $\sigma_2 : \text{Modules} \rightarrow \text{Sorts} \quad (\implies \quad \text{Places} \rightarrow \text{Sorts})$

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 $\sigma_2 : \text{Modules} \rightarrow \text{Sorts} \quad (\implies \quad \text{Places} \rightarrow \text{Sorts})$
- **Hypermarking** $\mu : \mathcal{N} \rightarrow \mathcal{P}_{\mathcal{N}}$ (*compatible* with the typing)
- *Tree-like* containment **hierarchy**.

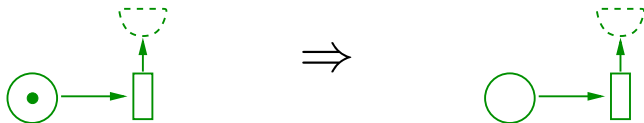
The agent hierarchy may change: *virtual places*

Virtual places specify how tokens may change level in the hierarchy

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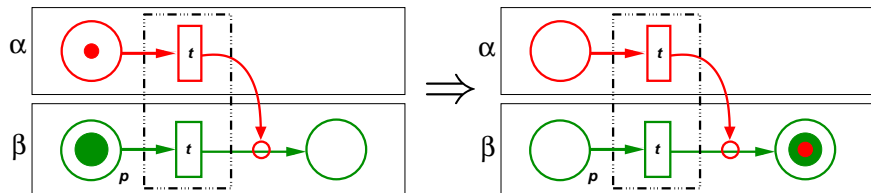
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1. Between an agent and its super-agent



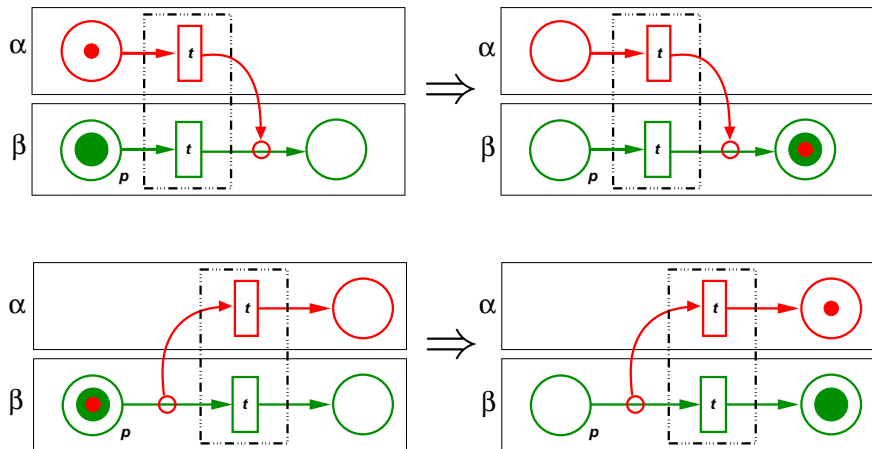
Virtual places

2. Within the same agent: inter-module exchange of tokens



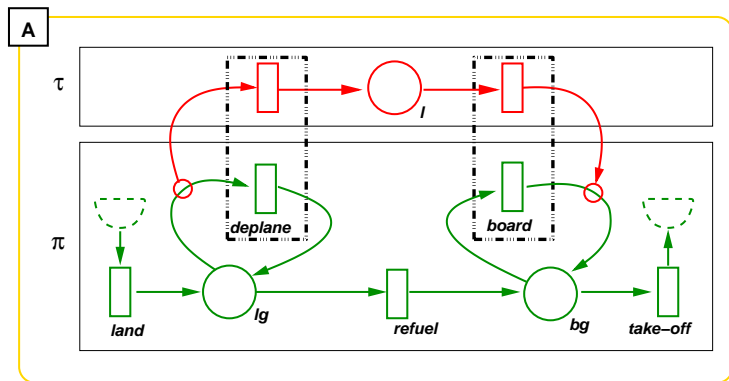
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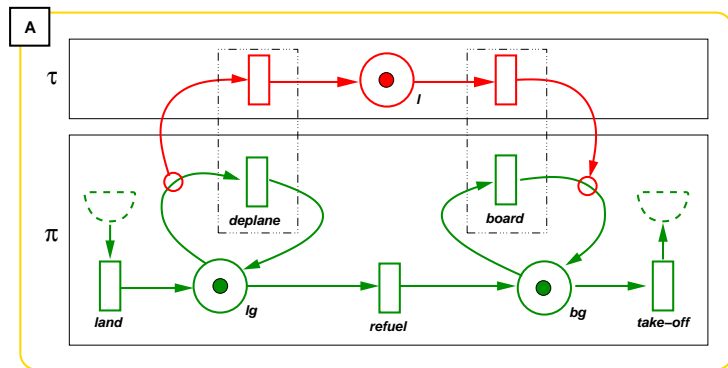
Example – modelling an airport

- An airport agent A with modules for planes (π) and travellers (τ)



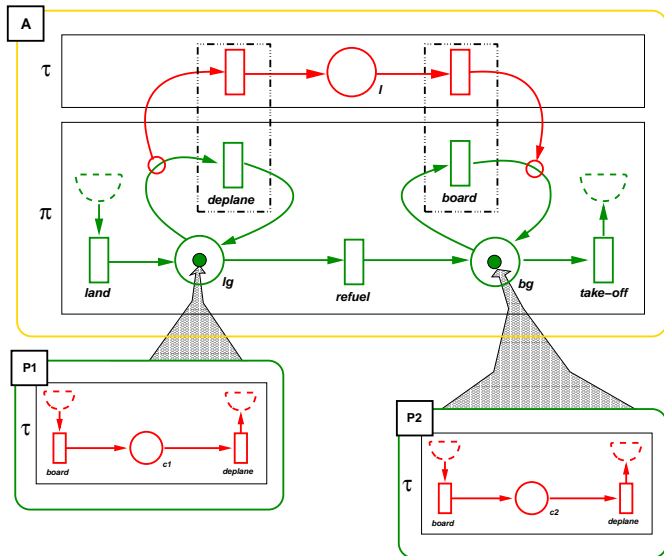
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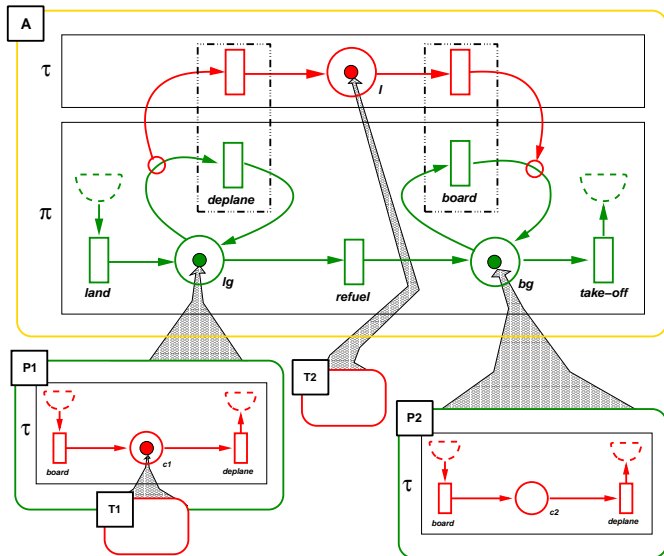
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Dynamics—building a consortium

The state of the system (i.e., the hypermarking) changes by firing consortia

A *consortium* is made by:

- the name of a transition t
- a set of *active agents* (containing t) moving other agents
- a set of *passive agents* being moved by their *super-agents*

Remark: an agent can be both *active* and *passive*

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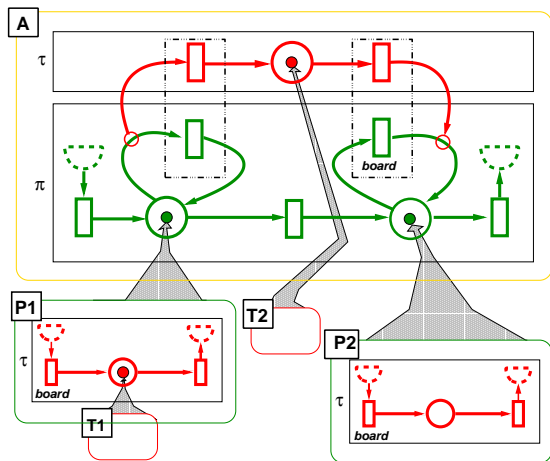
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Firing a consortium

the t transitions are fired *synchronously*

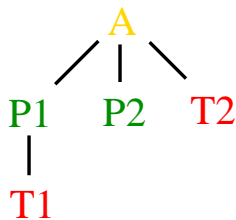
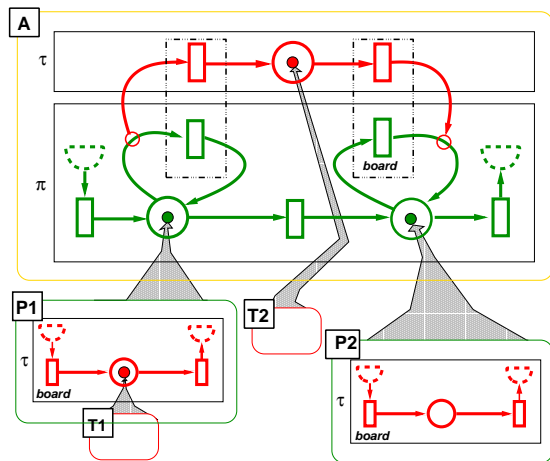
Dynamics—firing a consortium

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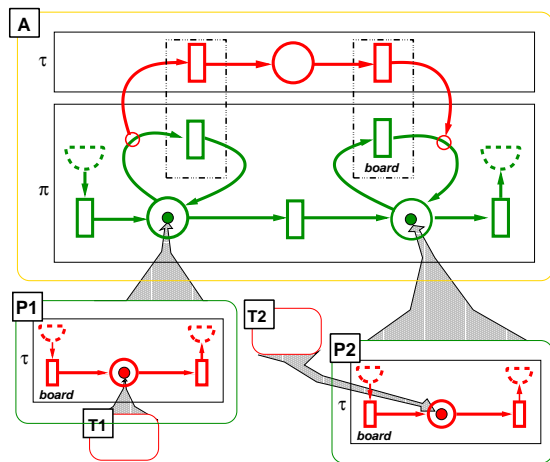
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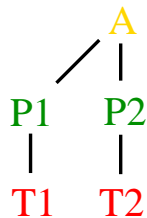
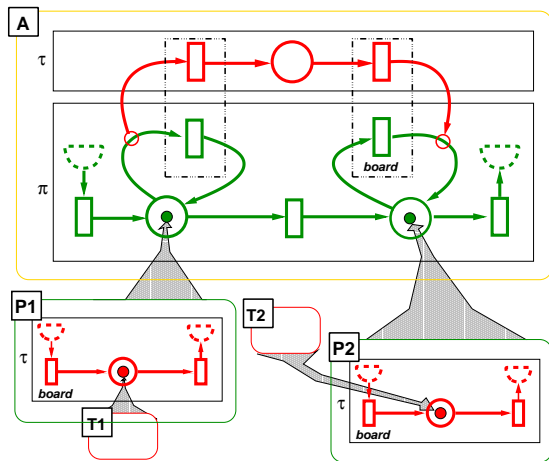
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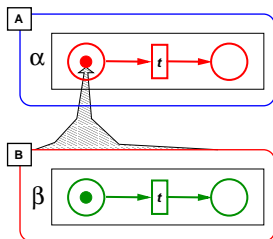


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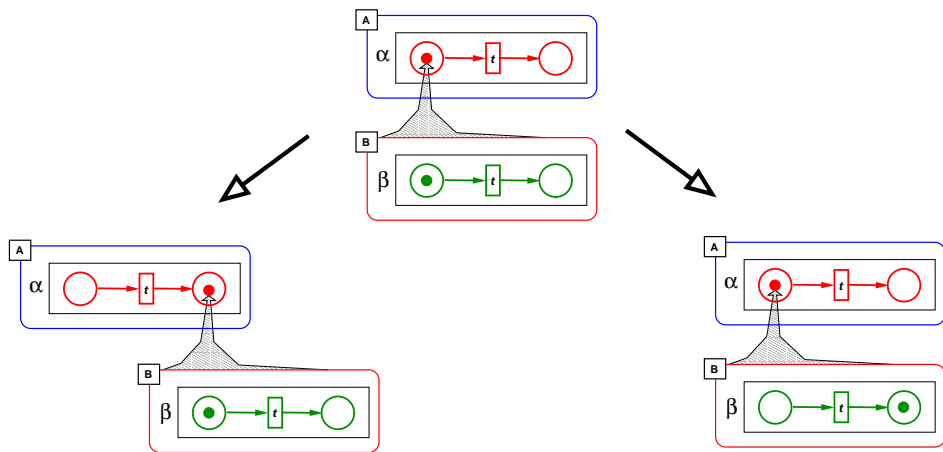
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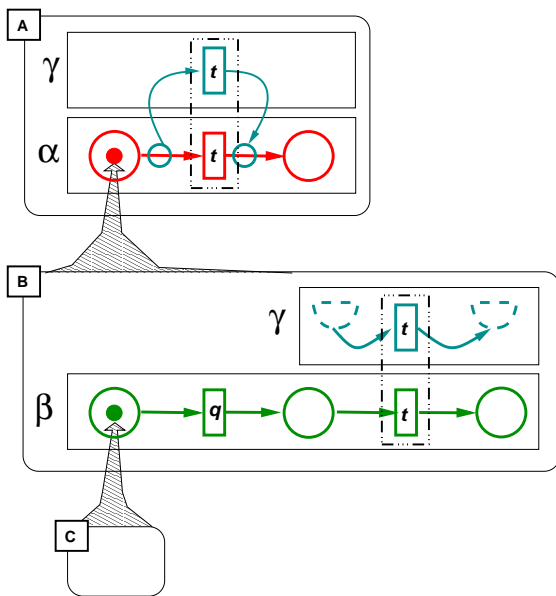
Two independent consortia



Two independent consortia



Inter-level synchronization via short loop



boundedness

Petri Hypernets are such that there is *no* creation *no* destruction of agents

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Theorem: Tree-like Structure Preservation

Let $\langle \mathcal{N}, \mu \rangle$ be a Petri Hypernet, \mathcal{M} a hypermarking, Γ a consortium enabled in \mathcal{M} , and \mathcal{M}' be the hypermarking reached after executing Γ . If the agent's hierarchy induced by \mathcal{M} is a *tree*, then the agent's hierarchy induced by \mathcal{M}' is also a *tree*.

SECTION 3

From Petri Hypernets to a basic Petri net class (1-safe nets)

From Petri Hypernets to 1-safe nets

$$\mathcal{F} : \langle \mathcal{N}, \mu \rangle \longrightarrow N = (B, E, F, M_\mu)$$

From Petri Hypernets to 1-safe nets

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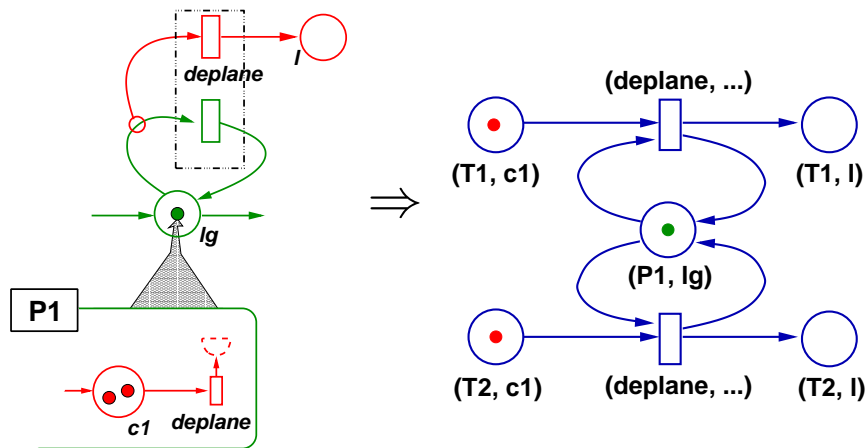
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- B conditions: $\langle p, A \rangle$ "agent A is in place p ";
- E events: "potential consortia";
- $\langle p, A \rangle \in M_\mu \iff \mu(A) = p$.

From Petri Hypernets to 1-safe nets – an example



From Petri Hypernets to 1-safe nets

$$\mathcal{F} : \langle \mathcal{N}, \mu \rangle \longrightarrow N = (B, E, F, M_\mu)$$

N is such that:

- each event is *balanced* (i.e.: $|pre(e)| = |post(e)|$);
- N is *1-safe*;

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- N is *1-safe*;
- N is *state machine decomposable*;
- the *hyper-marking graph* of $\langle \mathcal{N}, \mu \rangle$ is isomorphic to the *case graph* of N .

Hypermarkings of $\langle \mathcal{N}, \mu \rangle$ and reachable markings of N

Theorem

A consortium Γ is enabled at a hypermarking \mathcal{M} of $\langle \mathcal{N}, \mu \rangle$ iff the corresponding transition t_Γ is enabled at the marking $f(\mathcal{M})$ of N .

The execution of t_Γ leads to a marking which corresponds to the hypermarking reached after executing Γ

Hypermarkings of $\langle \mathcal{N}, \mu \rangle$ and reachable markings of N

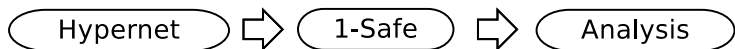
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Consequences

- All the analysis techniques available for 1-safe nets can be applied to Petri Hypernets;
- all the properties decidable for 1-safe nets are decidable for Hypernets, too.



From Petri Hypernets to 1-safe nets

Analysis of a Hypernet through the analysis of the 1-safe net

- place-invariants:
 - some specific ones identify the structural components of the Hypernet
(for ex.: all places where an agent can be hosted)

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- "In the future":
define invariants and other analysis technique directly on Hypernets.

Further work on Petri Hypernets

- Agent Aware Transition systems, as a behavioral model of mobile agents and as a basis for model checking Petri Hypernets. ²
- A logic for specifying temporal and structural properties of Petri Hypernets, towards model checking (by the IPI-PAN group). ³

²M. A. Bednarczyk, L. Bernardinello, W. Pawłowski, L. Pomello, Modelling and Analysing Systems of Agents by Agent-aware Transition Systems, 2008

³M. A. Bednarczyk, W. Jamroga, W. Pawłowski, Expressing and Verifying Temporal and Structural Properties of Mobile Agents. In *Fundam. Inform.*, 72(1-3): 51-63, 2006.

SECTION 4

From Petri Hypernets to Generalized hypertnets

From Petri Hypernets to Generalized hypertnets ⁴

Motivations

Petri Hypernets have some constraints which can be too strict, e.g.:

- typing of agents,
- the modular structure of agents, ...

⁴Marco Mascheroni's PhD thesis, University of Milano -Bicocca, 2011

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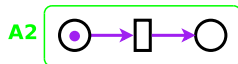
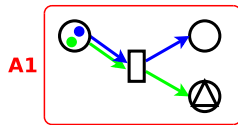
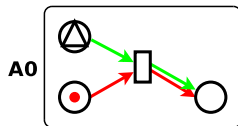
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New Features

- Use of *paths* \Rightarrow weighted arcs
- Multi-typed agents
- A more flexible synchronization between adjacent agents



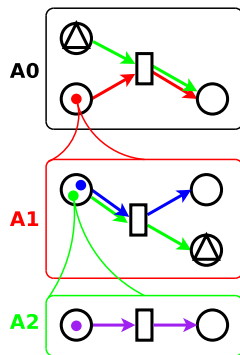
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Generalized hypernet Consortia

The state of the system (i.e., the hypermarking) changes by firing consortia

Elements of a Consortium

- A set of transitions (with the same label is chosen)

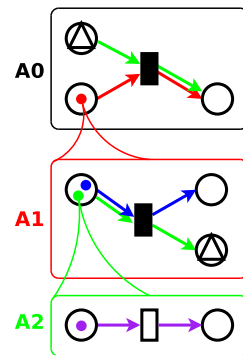


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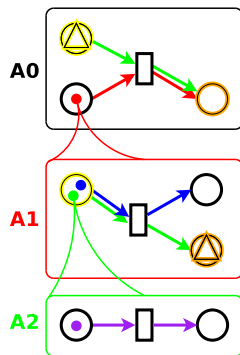


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- Binding virtual places

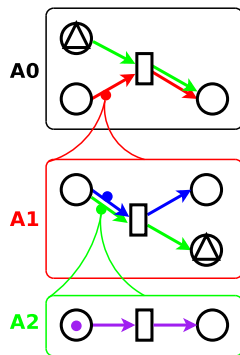


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- A set of transitions (with the same label is chosen)
- Binding virtual places
- Agent/Path association

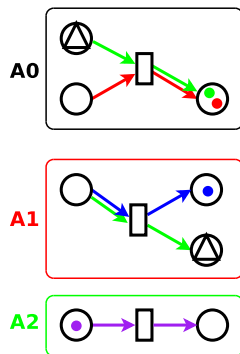


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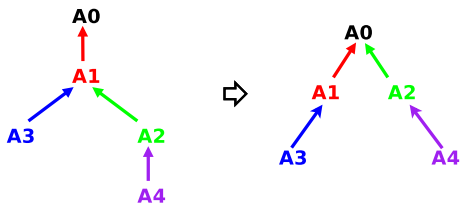
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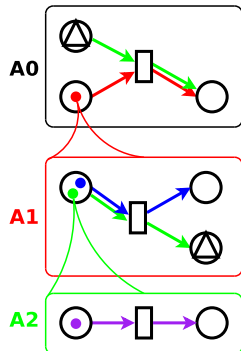
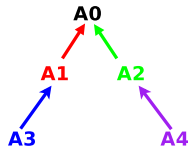
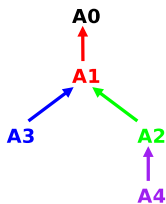
- A set of transitions (with the same label is chosen)
- Binding virtual places
- Agent/Path association
- The consortium can fire



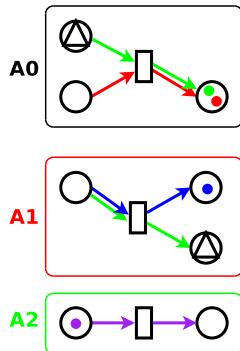
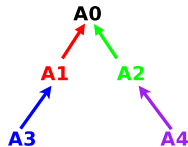
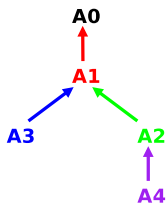
Hypermarking graph of Generalized hypernets



Hypermarking graph of Generalized hypernets



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Generalized Hypernets: further results

- From Generalized Hypernets to 1-safe nets

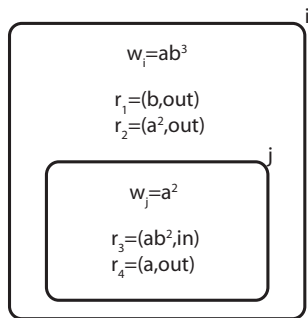
Generalized Hypernets: further results

- From Generalized Hypernets to 1-safe nets
- Definition of Unfolding of a Generalized Hypernet

SECTION 5

Two case studies

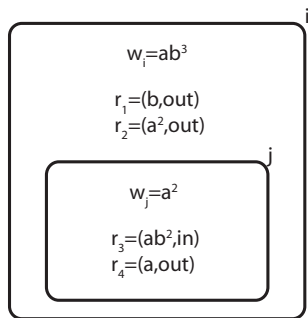
5.a) Modeling a Class of Membrane Systems



P Systems with Symport-Antiport Rules

- Bioinspired computational models
- Nested membranes which contain molecules and rules
- Rules change the configuration of the system

5.a) Modeling a Class of Membrane Systems

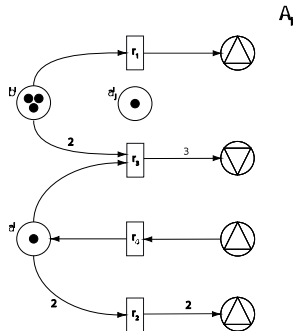


P Systems with Symport-Antiport Rules

- Bioinspired computational models
- Nested membranes which contain molecules and rules
- Rules change the configuration of the system

Modeling P systems

- Each membrane is an agent
- Molecules are tokens
- Rules are transitions
- Bijection g between hypermarkings and configurations



Theorem

Let Π be a P system, and let $\langle \mathcal{N}, \mu \rangle$ be the Hypernet which models it.
If a set of rules ρ is enabled in a configuration C of Π , **then** the set of consortia U , which correspond to ρ , are enabled in the hypermarking $g(C)$.
If C' is the configuration reached after executing ρ , **then** $g(C')$ is the hypermarking reached after firing U .

⁵L. Bernardinello, N. Bonzanni, M. Mascheroni, L. Pomello. Modeling symport/antiport p systems with a class of hierarchical Petri nets. In *Membrane Computing*, of *LNCS 4860*, p. 124–137, 2007..

Modeling a Class of P Systems ⁵

Theorem

Let Π be a P system, and let $\langle \mathcal{N}, \mu \rangle$ be the Hypernet which models it. **If** a set of rules ρ is enabled in a configuration C of Π , **then** the set of consortia U , which correspond to ρ , are enabled in the hypermarking $g(C)$. **If** C' is the configuration reached after executing ρ , **then** $g(C')$ is the hypermarking reached after firing U .

Possible Applications

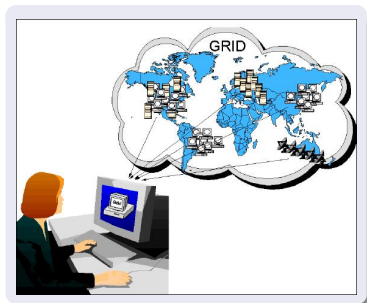
Then it is possible to use Petri nets analysis techniques to analyze P system.

⁵L. Bernardinello, N. Bonzanni, M. Mascheroni, L. Pomello. Modeling symport/antiport p systems with a class of hierarchical Petri nets. In *Membrane Computing, of LNCS 4860*, p. 124–137, 2007..

5.b) Modeling Grid Applications⁶

Grid Computing

- Analysis of data which are distributed in different data centers at different levels
- Final user should not care of data distribution
- Tools, which make easier the access to the Grid, are developed

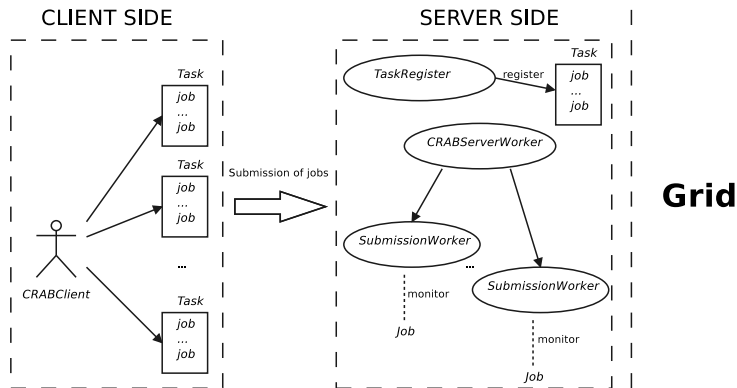


⁶M. Mascheroni, F. Farina, Nets within nets paradigm and grid computing. In ToPNoc, p. 201–220, 2012.

5.b) Modeling Grid Applications

- Is the Nets Within Nets Paradigm suitable to model/specify applications which use the Grid technology?
- Answer by modeling a Grid distributed data analysis tool serving the community of the Compact Muon Solenoid (CMS) experiment at the CERN Large Hadron Collider (LHC).

The CRAB Tool



- Split user's work into jobs and analyze datasets in parallel through the Grid
- CRAB (CMS Remote Analysis Builder) has a client-server architecture
- Sends/monitors/retrieves output of jobs from the Grid

Modeling Grid Applications

The submission use case of the CMS Remote Analysis Builder (CRAB) have been modeled by using Nets-Within-Nets, and in particular by using the tool RENEW (developed in Hamburg Univ.)

Results

Nets within nets seems to be a promising approach for modeling Grid applications:

- The hierarchical structure of the system is represented in the model;
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- some bugs in the software have been identified;
- Marco Mascheroni got a job at CERN, ::)), he is now in the group developing a new version of the tool (CRAB3)

SECTION 6

Conclusions

Petri Hypernets: a summary

A hierarchical model for mobile agents in the *nets-within-nets* paradigm

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- Its semantics is given in terms of a basic net class
- They have been generalized and applied

Future work . . .

- relax some constraints of the model, e.g.:
 - ▶ add the possibility to create/destroy agents;
 - ▶ allow interactions among agents in the same location without the participation of their superagent

⁷[M. A. Bednarczyk, W. Jamroga, W. Pawlowski, Expressing and Verifying Temporal and Structural Properties of Mobile Agents. In *Fundam. Inform.*, 72(1-3): 51-63, 2006.

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- a possible collaboration with the PAIS Lab combining *Nested Petri Nets* and *Peri Hypernets* ?

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THANK YOU
for your attention !

Спасибо большое !

GRAZIE!